



$A_1$  -  $\omega_1$  -  $t$  -  $\phi_1$   $\omega_1$   $\varphi_0$   $A_0$   $h$  /  
 $\phi_1$   $\omega_1$   $\varphi_0$   $A_0$   $h$  /  
 $\omega_0$  /

$$Y(A_0, \omega_0, \varphi_0, t) = \frac{A_0}{\sqrt{h}} [\cos(\omega_0 t) \cos(\varphi_0) - \sin(\omega_0 t) \sin(\varphi_0)] \quad (2)$$

$Z(A_1, \omega_1, \phi_1, A_0, \omega_0, \varphi_0, t) = X(A_1, \omega_1, \phi_1, t) + Y(A_1, h, \omega_0, \varphi_0, t) \quad (3)$

$\omega_0 = n_0 \cdot \omega_1 \quad (4)$   
 $\phi_0 \in [-\pi/2, \pi/2]$   
 $n_0 = \dots$   
 $\varphi_0 = \frac{k}{n_1} \frac{\pi}{2}, \quad k = 1, 2, 3, \dots, n_1 \quad (5)$

$$Z(t, h, n_0, k) = A_1 \left[ \cos(\omega_1 t - \phi_1) + \frac{1}{\sqrt{h}} \cos(n_0 \omega_1 t - \frac{k \pi}{n_1}) \right] \quad (6)$$

**Основна частина**

$S(A_1, \omega_1, \phi_1) = \sum_t^T [Z(h, n_0, k, t) - X(A_1, \omega_1, \phi_1, t)]^2, \quad (7)$   
 $T_2$

$\sum_t [Z(h, n_0, k, t) - X(A_1, \omega_1, \phi_1, t)] \cos(\omega_1 t - \phi_1) = 0 \quad (8)$   
 $\sum_t [Z(h, n_0, k, t) - X(A_1, \omega_1, \phi_1, t)] \sin(\omega_1 t - \phi_1) = 0 \quad (9)$

$$\sum_t [Z(h, n_0, k, t) - X(A_1, \omega_1, \phi_1, t)] \sin(\omega_1 t - \phi_1) = 0 \quad (10)$$

$$A_{1opt} = \frac{\sum_t [Z(h, n_0, k, t) \cos(\omega_1 t - \phi_1)]}{\sum_t \cos(\omega_1 t - \phi_1)^2} \quad (11)$$

$$\begin{aligned} & \sum_t [Z(h, n_0, k, t) \cos(\omega_1 t - \phi_1)] \\ & \sum_t \cos(\omega_1 t - \phi_1)^2 \end{aligned} \quad (14)$$

$$LP1(\omega_1) = \sum_t X(A_1, \omega_1, \phi_1, t) \sin(\omega_1 t - \phi_1) t, \quad (12)$$

$$RP1(\omega_1, h, n_0, k) = \sum_t Z(h, n_0, k, t) \sin(\omega_1 t - \phi_1) t, \quad (13)$$

$$\Delta LP1(\omega_1, h, n_0, k) = LP1(\omega_1) - RP1(\omega_1, h, n_0, k). \quad (14)$$

$$LP2(\phi_1) = \sum_t X(A_1, \omega_1, \phi_1, t) \sin(\omega_1 t - \phi_1), \quad (15)$$

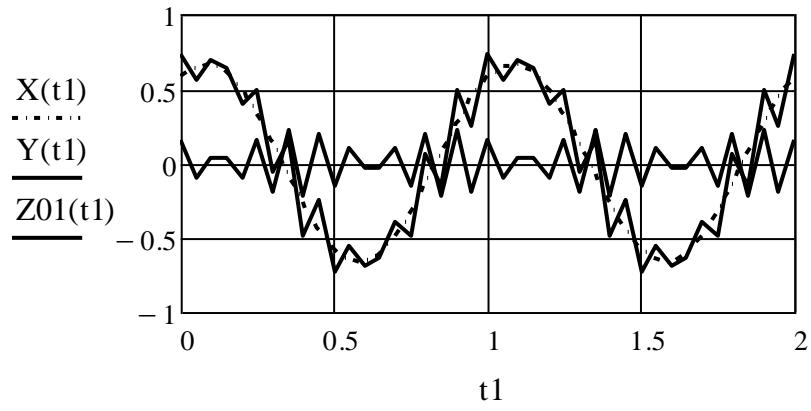
$$RP2(\phi_1, h, n_0, k) = \sum_t Z(h, n_0, k, t) \sin(\omega_1 t - \phi_1), \quad (16)$$

$$\Delta LP2(\phi_1, h, n_0, k) = LP2(\phi_1) - RP2(\phi_1, h, n_0, k). \quad (17)$$

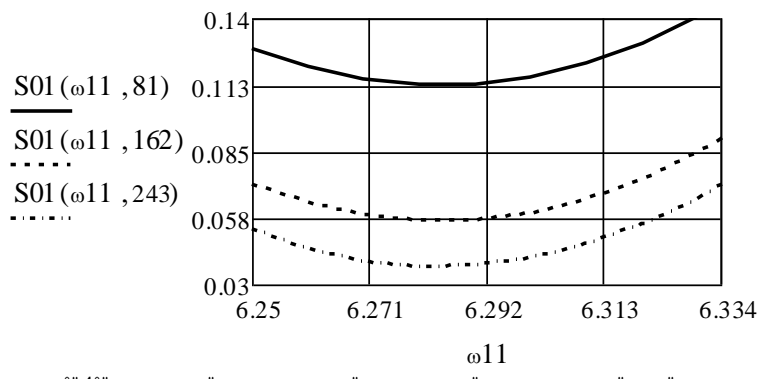
$$\Delta l(\omega_1, h2, n_0, k) \sqrt{h2} = \Delta l(\omega_1, h1, n_0, k) \sqrt{h1}, \quad (18)$$

$$\frac{\Delta l(\omega_1, h2, n_0, k)}{\Delta l(\omega_1, h1, n_0, k)} = \frac{\sqrt{h1}}{\sqrt{h2}} \quad (19)$$

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